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Exercise 2: Let F be the field of complex numbers. Are the following two systems of linear equations equivalent? If so, express each equation in each system as a linear combination of the equations in the other system. $x_1 + x_2 = 0$ $3x_1 + x_2 = 0$ $2x_1 + x_2 = 0$ $x_1 + x_2 = 0$ Solution: Yes the two systems are equivalent.

Linear Algebra - Greg Grant

Linear Algebra 2nd Edition by Kenneth M Hoffman, Ray Kunze (see solutions here) Good Linear Algebra textbooks (not complete) Introduction to Linear Algebra, Fifth Edition by Gilbert Strang, Solution Manual; Linear Algebra and Its Applications (5th Edition) by David C. Lay, Steven R. Lay, Judi J. McDonald

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Solution: Since T has n distinct characteristic values, T is diagonalizable (exercise 6.2.7, page 190). Choose a basis B for which T is represented by a diagonal matrix A . Suppose the linear transformation S commutes with T . Let B be the matrix of S in the basis B .

Solution to Linear Algebra Hoffman & Kunze Chapter 6.5

Chapter 1: Linear Equations. Linear algebra is, after all, motivated by systems of linear equations. A novel feature of Hoffman and Kunze is that most of their theorems and proofs generalize the

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concepts of the real/complex numbers into arbitrary "fields" of "scalars."

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Solution to Linear Algebra Hoffman & Kunze Chapter 3.4

Solve this system of linear equations. Linearly independent solutions of this system will form a basis for W . Set x_1 and x_2 as free variables. Assign values c to x_1 and d to x_2 . That is, set $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix}$. Then. From (1), Thus, solutions of (1) and (2) are of the form $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} c \\ d \\ \dots \\ \dots \end{pmatrix}$. Find two particular solutions by assigning different values to c and d . Set $c=1, d=0$. This gives $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ \dots \\ \dots \end{pmatrix}$. Set $c=0, d=1$. This gives $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ \dots \\ \dots \end{pmatrix}$. Set ...

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